GTH SERIES

Parallel Twin-Spindle CNC Turning Centers

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PARALLEL TWIN-SPINDLE CNC TURNING CENTER

With leading technology and high quality components, the GTH series is particularly developed for automobile industry. By applying advanced parallel twin spindles, twin turrets structure and high efficiency automation system, the GTH provides automatic loading, front/rear cutting, unloading and work-piece detecting, which make its ultimate machining capabilities a coordinated process. Furthermore, the GTH series fulfills all types of plate-shape and short-shaft work-piece of automatic mass production needs.

- Major structure adopts modular design which based on machining requirements, machine can be promoted to be an optimal production line, which highly reduces cost of manpower and increases production efficiency. (see page 4)
- Parallel twin-spindle structure can reduce turret interference, which can fulfill precise machining accuracy of large plate-shape work piece.
- Z-axis traverse is designed as a combination of saddle and bed which its rigidity performs much better than quill type.



(GTH-2600 model shown with optional accessories)



1 Back-Exit Chip Conveyor

Back-exit chip conveyor is good for production arrangement of centralizing chips.

2 Front-Pull Type Coolant Tank

Large quantity of separated coolant tank adopts front-pull design, and features front installation of collecting chips, which can reduce space of operation and maintain conveniently.

3 Movable Protection Door for Chips Spilling

- Prevent any hazard of chips spilling from the machining operation zone to the loading operation zone.
- Movable protection door can increase the space of operation and much more convenience to setup work-pieces or tools.







HEAVY-DUTY CONSTRUCTION

By using Finite Element Analysis (FEA) and high tension Meehanite casting structure, super rigidity frame of spindles, turrets and saddle are reaching the optimal reinforcement. Mechanical strength is well enough to load extremely heavy cutting while maintaining long period of super high accuracy. Moreover, super rigidity of machine can extend life time of tools.

- Parallel twin-spindle structure adopts modular isolating bed design which can efficiently decrease cutting resonance of two spindle systems and increase reliability of machining, roundness and roughness of appearance.
- Major structural components of machine are united into one solid platform. The low center of gravity design provides firmly stable headstock and turret.
- X / Z axes adopt super rigidity box ways design which is through heat treatment and precise finishing processes. And long span design of traverse can maximize strength and precision. Box way design also provides the rigidity needed for heavy-duty and interrupted turning applications.
- Contact surfaces of all slides, headstock, turret, and ball screw bearing housings with the machine bed are precision hand scraped to provide maximum assembly precision, structural rigidity, and load distribution.





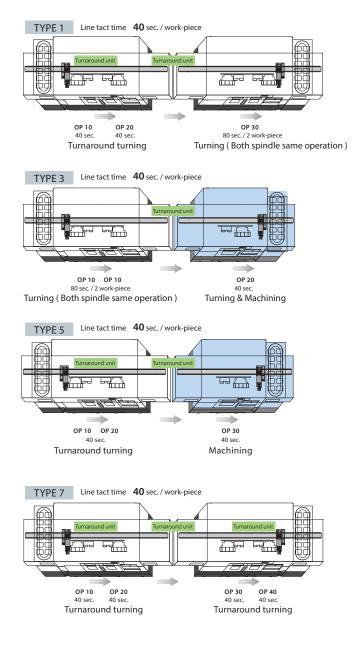
Z-axis super rigidity structure

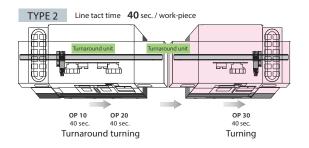
Saddle features bed structure

Full travel of saddle and turret are firmly supported by bed, and distance of overhang of turret is shorter which increase cutting rigidity.



Varies applications



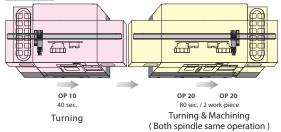




OP 10 80 sec. / 2 work-piece Turning (Both spindle same operation)

OP 20 80 sec. / 2 work-piece Turning & Machining (Both spindle same operation)

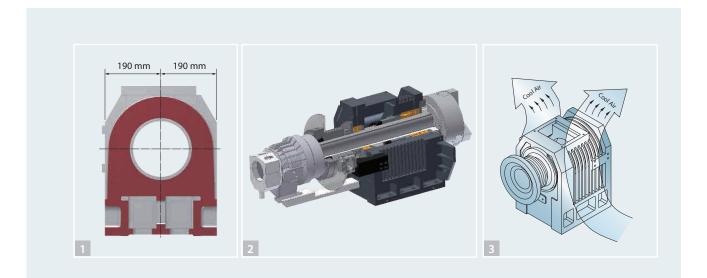
Line tact time 40 sec. / work-piece TYPE 6



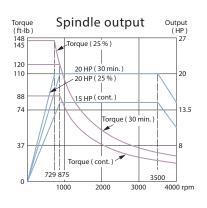
TYPE 8 Line tact time 40 sec. / work-piece ст. 83 ᇳᆋ OP 10 OP 10 160 sec. / 2 wor-kpiece Turning (Both spindle same operation يي ĘЯ OP 10 OP 10 160 sec. / 2 work-piece Turning (Both spindle same operation)

3

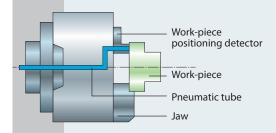
ULTIMATE MACHINING POWER



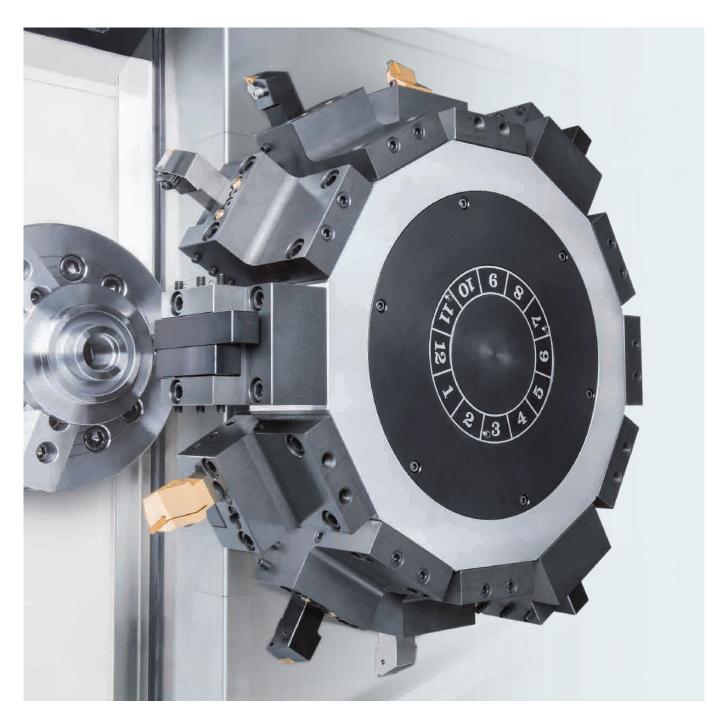
- **1** Head stocks feature even thickness sides, which evenly distribute cutting forces to the machine bed, resulting in exceptional vibration dampening characteristics and forms a stronger structure to handle interrupted and heavy cutting applications.
- **2** P4 grade (Class 7) super-high precision bearings are directly assembled for maximum level of support and precision. Bearing configuration is designed for super heavy-duty cutting with ultra-smooth performance and long term durability with a higher level of accuracy.
- 3 Heat dispensing fins around the headstock evenly dispense heat to reduce deformation, therefore, increasing machining accuracy.



Optional Pneumatic Work-Piece Positioning Detector

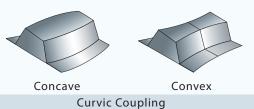


Apply pneumatic flow to detect work-piece and fit of clamping jaw surface. When not adjust closely to fit, robot arm will re-load again to ensure operation safety.



ADVANCED TURRET TECHNOLOGY

- Heavy-duty servo indexing turret achieves 0.2 second indexing times for adjacent stations and 0.5 second times for stations at the opposite end of the disk turret.
- Ø 210 mm (8.26") diameter super high precision CURVIC couplings accurately position the turret disk (± 2 sec. of arc) and 4,000 Kg of clamping force ensures abundant turret rigidity for all cutting conditions.
- The CURVIC coupling is provided with automatic centering, cleaning and super large contact area of tooth flank, which ensures long-term usage of cutting rigidity and positioning accuracy.



LIVE TOOLING TURRET

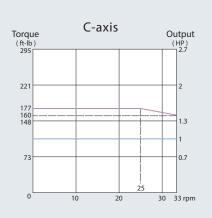


- The 12-station YAMA SEIKI live tooling turret offers 12 stations available for live tooling (live tooling tools rotate in working position only) and features a non-lifting turret disk.
- YAMA SEIKI's live tooling turret utilizes advance servo indexing technology to achieve 0.2 second indexing times for adjacent stations and 0.5 second for stations at the opposite end of the disk.
- With the latest technology, live tooling is driven by an AC servo motor to provide ample power, in the form of torque. Now, even the toughest of jobs may be tackled without a sweat.

ULTIMATE C-AXIS SPINDLE

- Working with the live tooling turret, the Cf-axis and disk brake system enables the machine to perform multiple tasks, such as drilling, tapping, and milling operations, including cylindrical and polar coordinate interpolations, resembling a 4th-axis rotary table on a machining center.
- With the FANUC servo motor generating an ultra high resolution of 33,000,000 pulses per spindle rotation and 480 N-m of spindle torque (Cont.), machined surface finishes are much superior than Cs-axis (driven by spindle motor) equipped machines. Plus, dynamic accuracy is within ± 0.02° even under heavy cutting loads.



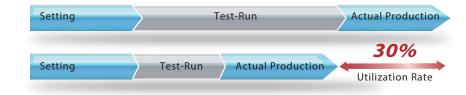


NC INTELLIGENCE

Advanced hardware combined with intelligent software, makes your machine smarter



Significant Production Efficiency



The 3D simulation inspection can greatly reduce test-run time and improve overall utilization rate

Comprehensive Functions

General Production

Using 3D Simulation

Process

Inspection

Programming Setting

- Program management Friendly programing
- environment
- Programming auxiliary
- Manual Guide i
- Embedded E-manual

Test-Run 3D advance tool

path and cutting

simulation

- Tool load monitor
- Program check
- Smart balance detection
- 3D Real-time cutting simulation and interference check

Actual Production Daily Used

Tool load monitor 3D Real-time cutting simulation and

interference check

- Safety signal viewer
- Fast alarm check productivity
- Productivity management
- Twin operation system switch
- Maintenance management

















AUTOMATIC PRODUCTION SYSTEM

Depend on different work-piece specifications and machining characteristics, YAMA SEIKI provides elastic configurations of automatic production system to ensure operation needs of high efficiency and unmanned machinery space.

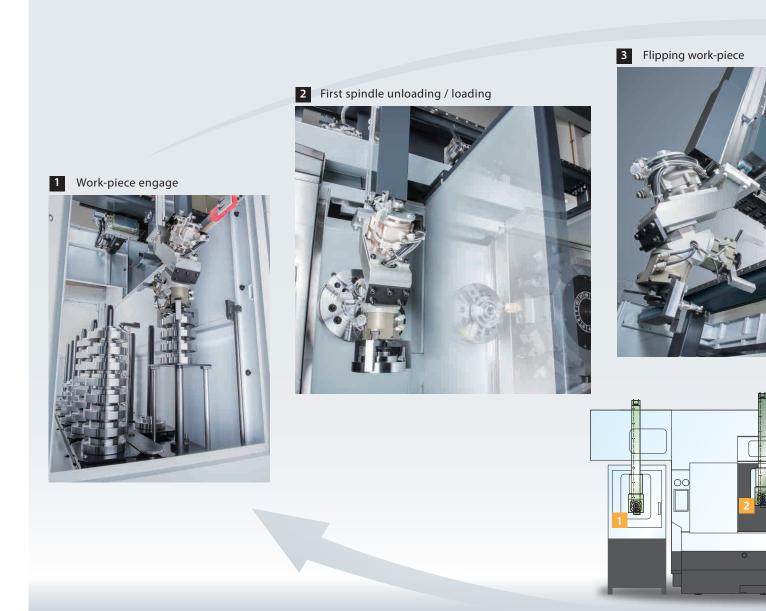
X-axis Rapids 2,500 (mm/sec.)

Gantry type loading / unloading system

| Loader work-piece handling capacity (weight) | | 3 Kg x2 |
|--|------------|------------------------|
| Loader work-piece handling capacity (size) | | Ø 150 x 80 mm |
| X-axis (Left / Right) | Stroke | 4,200 mm ^{*1} |
| | Max. speed | 2,500 mm/sec. |
| Y-axis (Up / Down) | Stroke | 800 mm |
| | Max. speed | 2,000 mm/sec. |
| Z-axis (Front / Rear) | Stroke | 210 mm |
| | Max. speed | 500 mm/sec. |
| C -axis | Stroke | 180° |
| | Max. speed | 1 sec. / 180° |

Specifications are subject to change without notice.

*1 Stroke varies from requirements.



Rotary Twin Jaws Robot Arm

Feature pneumatic work-piece positioning detector, unloading, positioning detector, loading can be done in one setup which is pretty safe and quick.

Work-piece Detecting System

Depend on actual needs to setup accuracy condition, qualified and unqualified products will be automatically distinguished, which efficiently saves manpower.



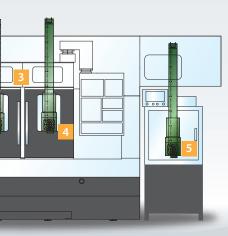


4 Second spindle unloading / loading



5 Work-piece detection / unloading

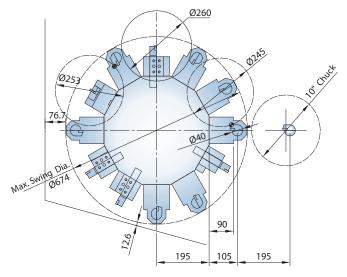


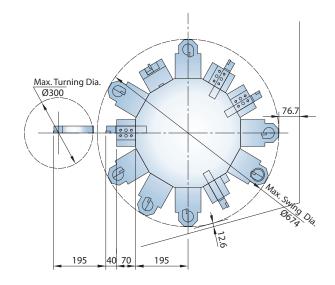


DIMENSIONS

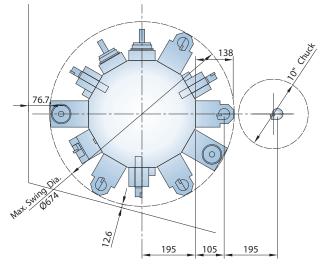
Interference Diagram

(Standard 12-Station Turret)



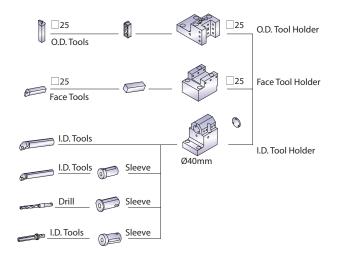


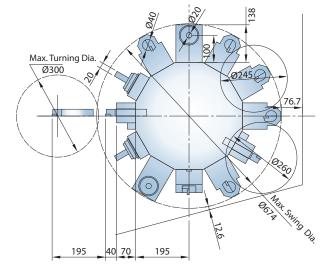
(12-Station Live Tooling Turret)



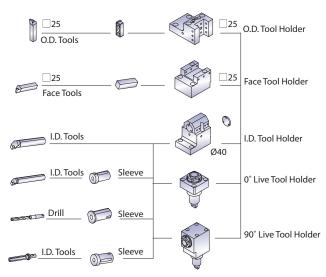
Tooling System

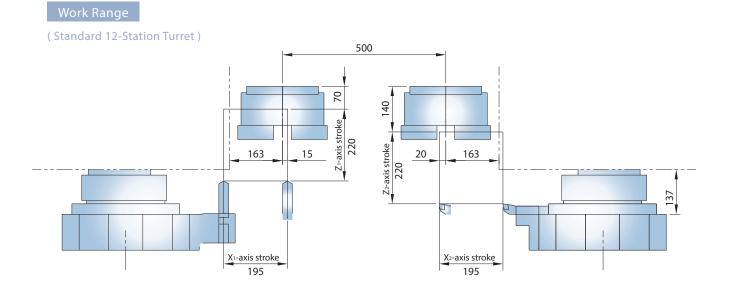
(Standard 12-Station Turret)

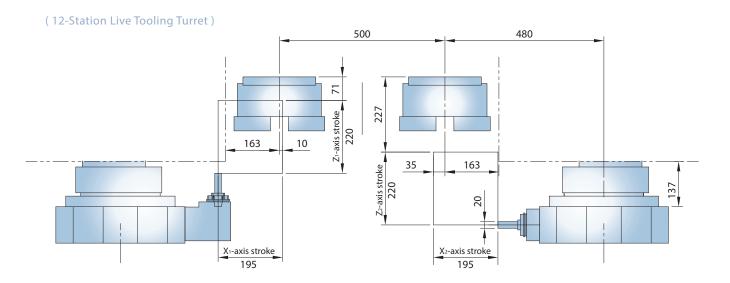


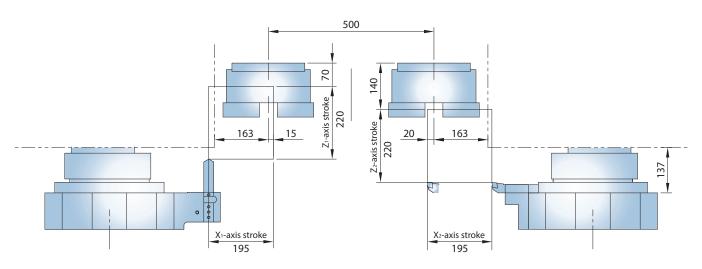


(12-Station Live Tooling Turret)









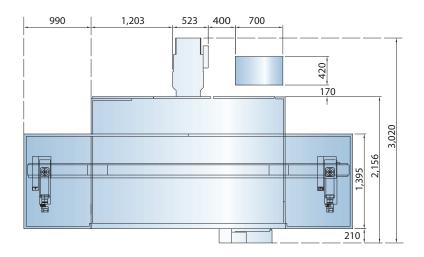
MACHINE SPECIFICATIONS

| CAPACITY | GTH-2600 | |
|---|--|--|
| Max. turning diameter | Ø 300 mm (Ø 11.81") | |
| Standard turning diameter | Ø 260 mm (Ø 10.23") | |
| Max. turning length | 205 mm (8.07") | |
| Chuck size | 10" | |
| SPINDLE | | |
| Hole through spindle | Ø 66 mm (Ø 2.59") | |
| Spindle bearing diameter(Front / Rear) | Ø 100 / Ø 90 mm (Ø 3.93" / Ø 3.54") | |
| Spindle nose | A2-6 | |
| Motor output (Cont. / 30min.) | 11 / 15 kW (15 / 20 HP) | |
| Motor full output speed | 1,500 rpm | |
| Spindle drive system | Direct Belt Drive | |
| Spindle speed range | 24 ~ 4,200 rpm | |
| Spindle full output speed | 860 rpm | |
| Spindle torque (Cont. / 30min.) | 120 / 162 N-m (88.5 / 119 ft-lb) | |
| Cf-AXIS (OPTIONAL) | | |
| Cf-axis motor | AC 1.2 kW (1.5 HP) | |
| Cf-axis rapids | 33 rpm | |
| Max. Cf-axis torque (Cont.) | 240 N-m (177 ft-lb) | |
| X & Z AXES | | |
| Max. X / Z axes travel | 195 / 220 mm (7.67" / 8.66") | |
| X / Z axes rapids | 24 m/min (944 IPM) | |
| Slide way type | Box way | |
| Feed rates | 1 ~ 500 mm/min (1 ~ 20 IPM) | |
| X / Z axes servo motor | AC 1.6 kW (2 HP) / AC 3 kW (4 HP) | |
| X / Z axes ball screw Ø / pitch | Ø 32 mm (Ø 1.25") / Pitch 8 | |
| X / Z axes thrust (Cont.) | 644 / 958 Kgf (1,419 / 2,112 lbf) | |
| TURRET | | |
| Station | 12 | |
| Indexing drive | FANUC AC Servo motor | |
| Indexing speed | 0.2 sec. (Adjacnt) / 0.5 sec. (180° Single step) | |
| OD tool shank size | | |
| ID tool shank size | Ø 1-1/2" | |
| LIVE TOOLING TURRET (OPTIONAL) | | |
| Max. turning diameter | Ø 300 mm (Ø 11.81") | |
| Live tooling stations | 12 (Opt. 16) | |
| Live tooling motor output (Cont. / 30 min.) | AC 3.7 / 5.5 kW (5 / 7.5 HP) | |
| Indexing drive | FANUC AC Servo motor | |
| Indexing speed | 0.2 sec. (Adjacnt) / 0.5 sec. (180° Single step) | |
| OD tool shank size | | |
| ID tool shank size | Ø 1-1/2" | |
| Live tooling shank size | ER32 (Ø 3/4") | |
| Live tooling RPM range | 6,000 rpm | |

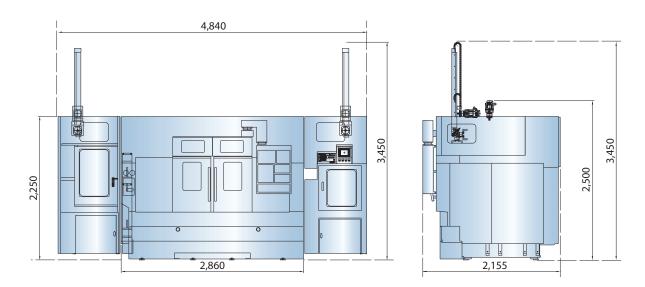
| GENERAL | GTH-2600 | |
|-----------------------------|--|--|
| CNC control | FANUC O <i>i</i> -TF (Opt. 31 <i>i</i>) | |
| Voltage / Power requirement | AC 220 V / 65 kVA | |
| Hydraulic tank capacity | 30 L (8 gal) | |
| Coolant tank capacity | 160 L (42 gal) | |
| Machine weight | 6,800 Kg (14,992 lb) | |
| Dimensions (L x W x H) | 4,840 x 2,155 x 3,450 mm (191" x 85" x 136") | |

Specifications are subject to change without notice.

Space Requirement



Machine Layout







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